



## Next generation pulsed time-of-flight sensors for autonomous driving

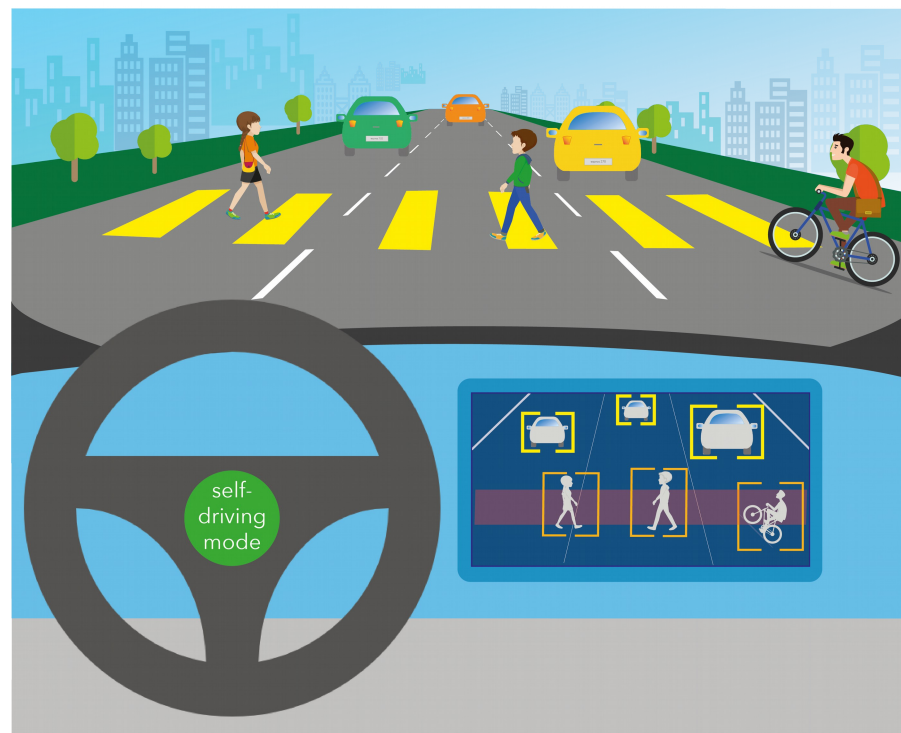
Beat De Coi

# Topics

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- ADAS requirements
- Sensor technology overview
- ESPROS CCD/CMOS technology OHC15L™
- Technology comparison of receiver elements
- Performance data of EPSORS OHC15L™ Imaging LiDAR
- A few words about the company

# Our driving future: The aim of ESPROS



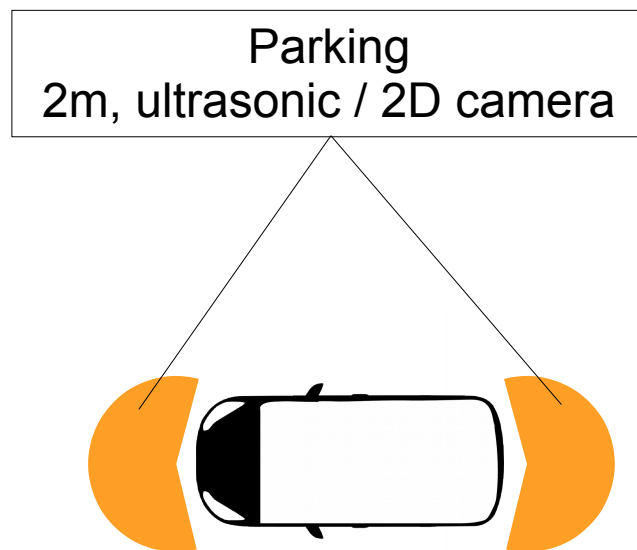
«Siri, drive me home, please!»

# Requirements and solutions today

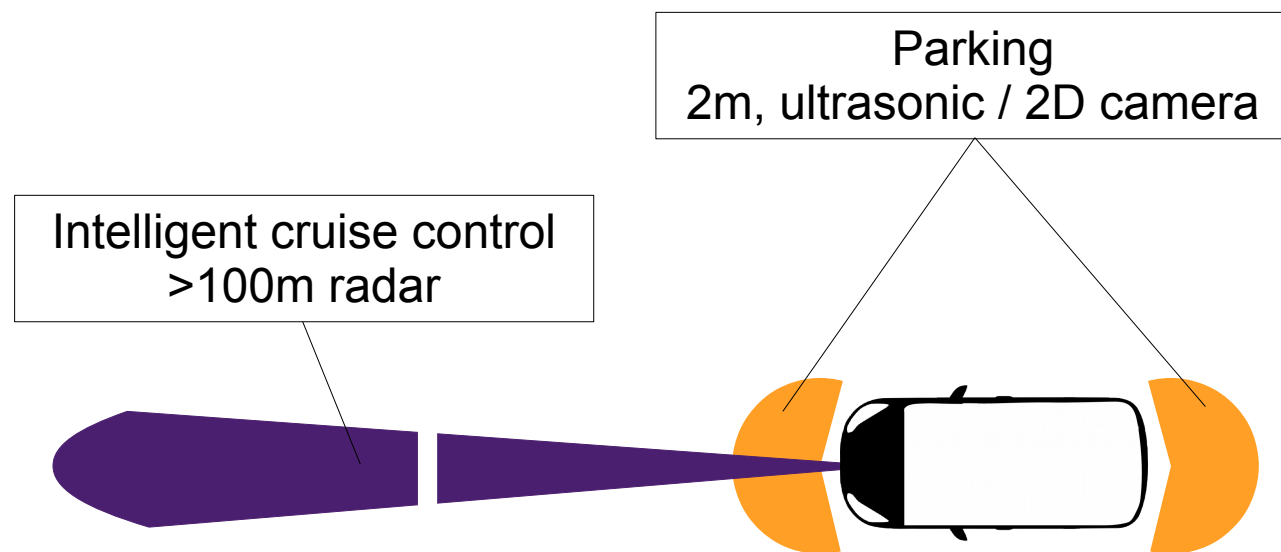
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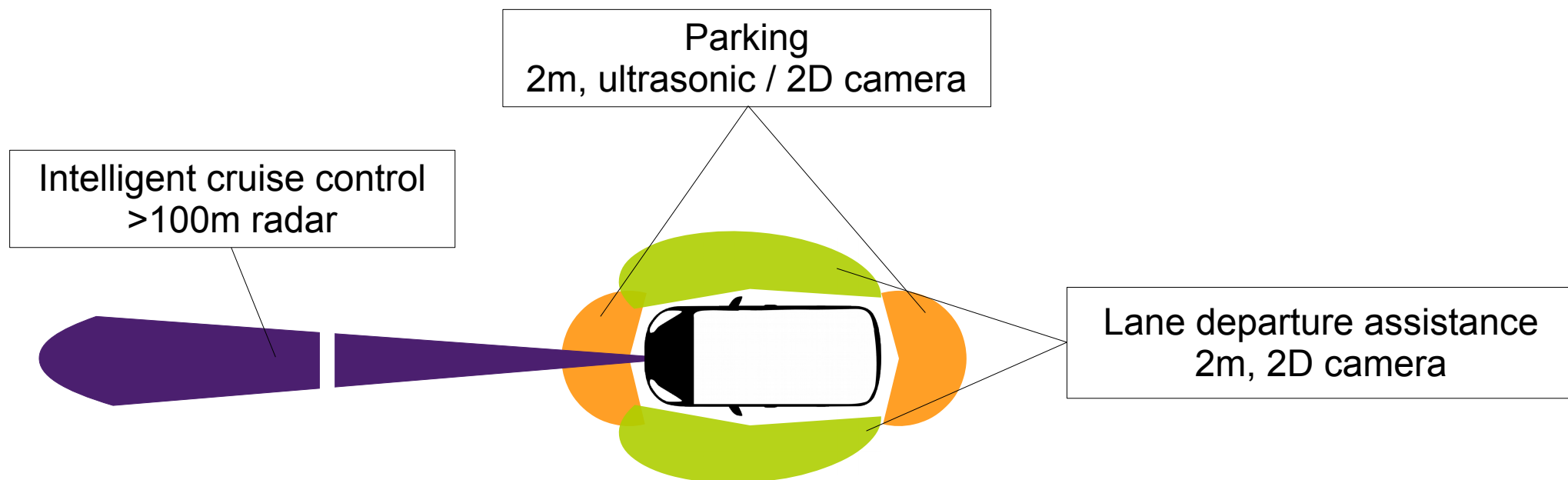
# Requirements and solutions today



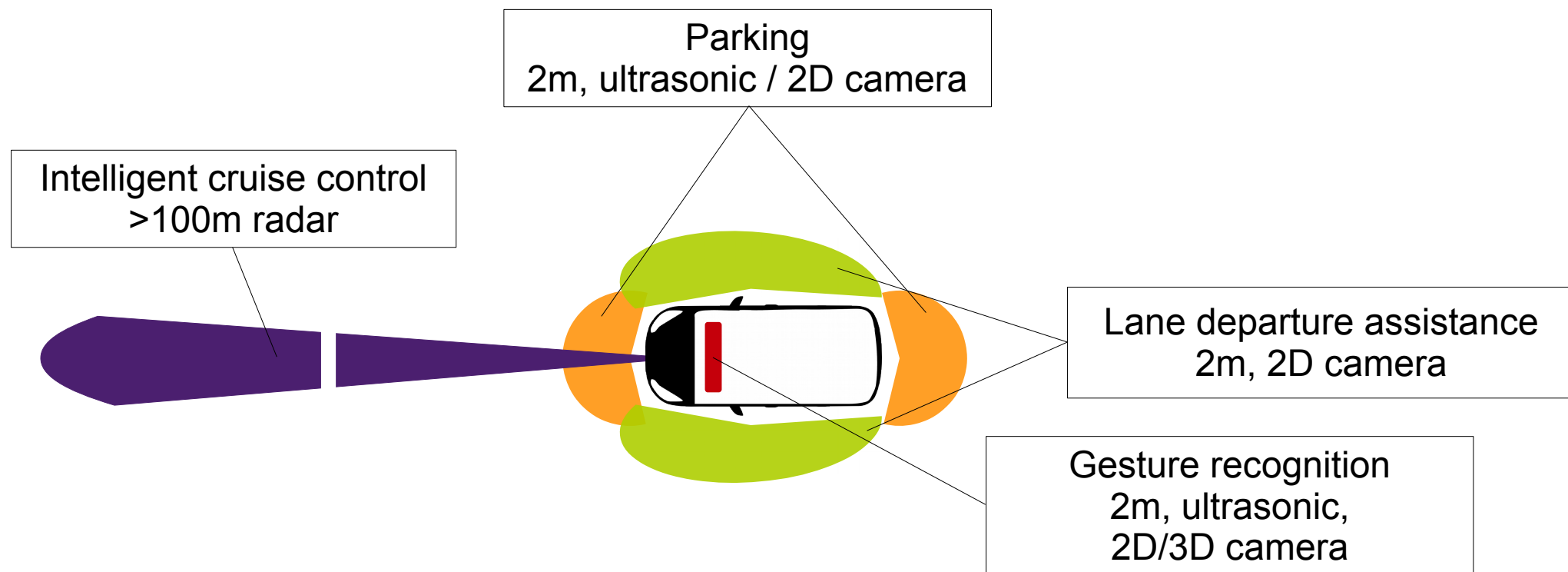
# Requirements and solutions today



# Requirements today

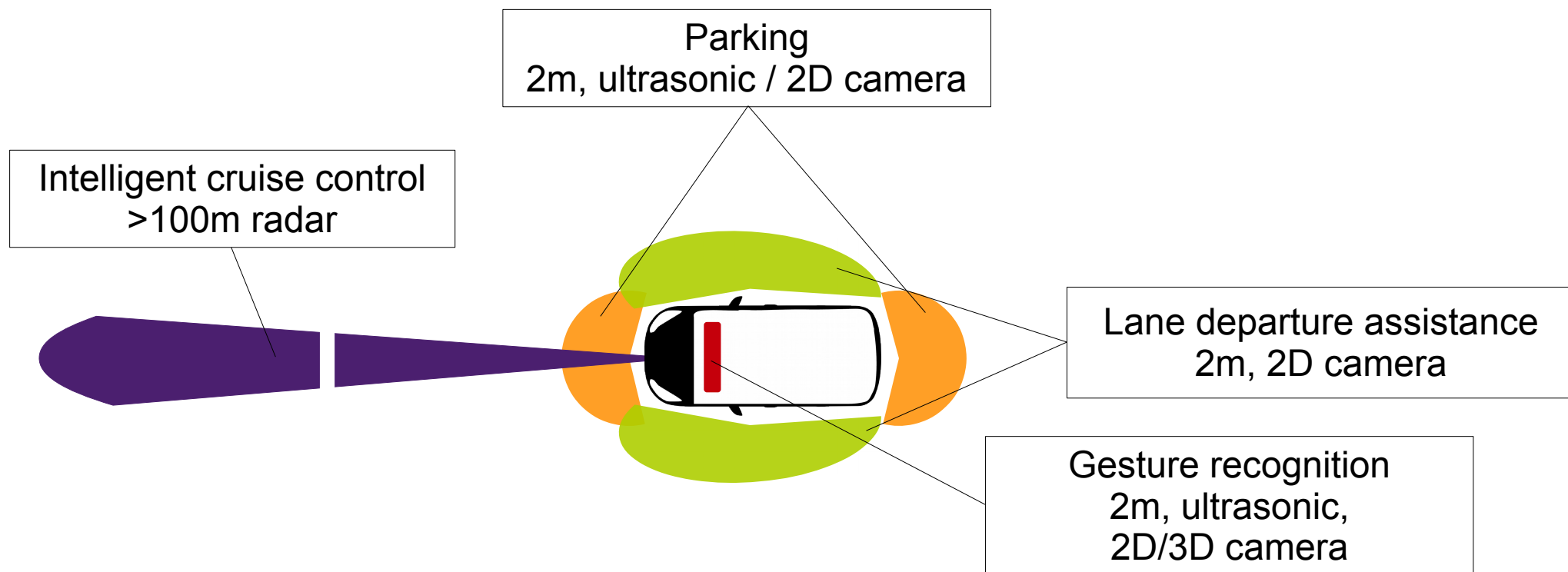


# Requirements today



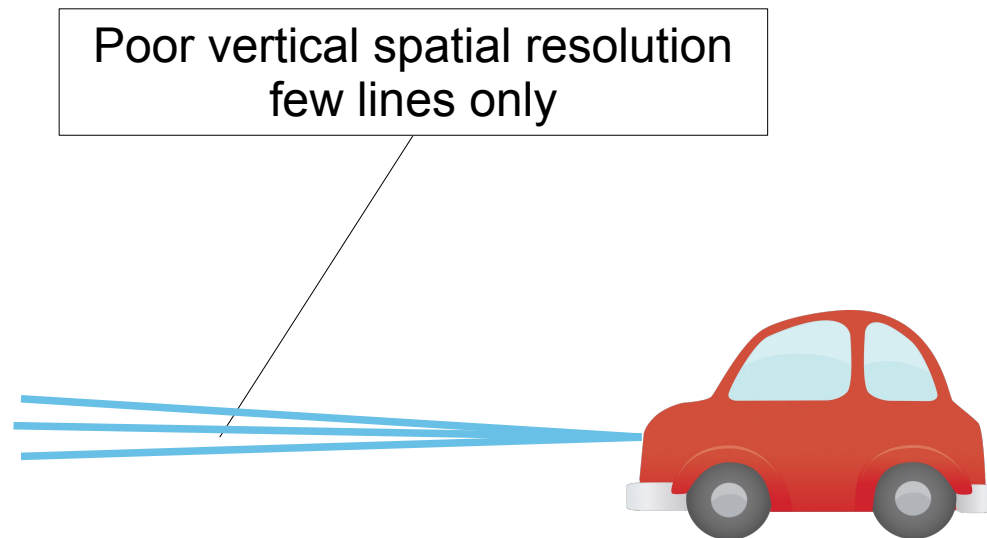


## Requirements today



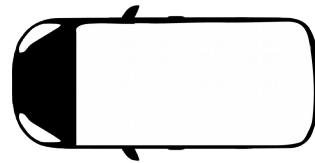
- Quite good sensors and technologies available
- Already well deployed and mature

# Current LiDAR solutions

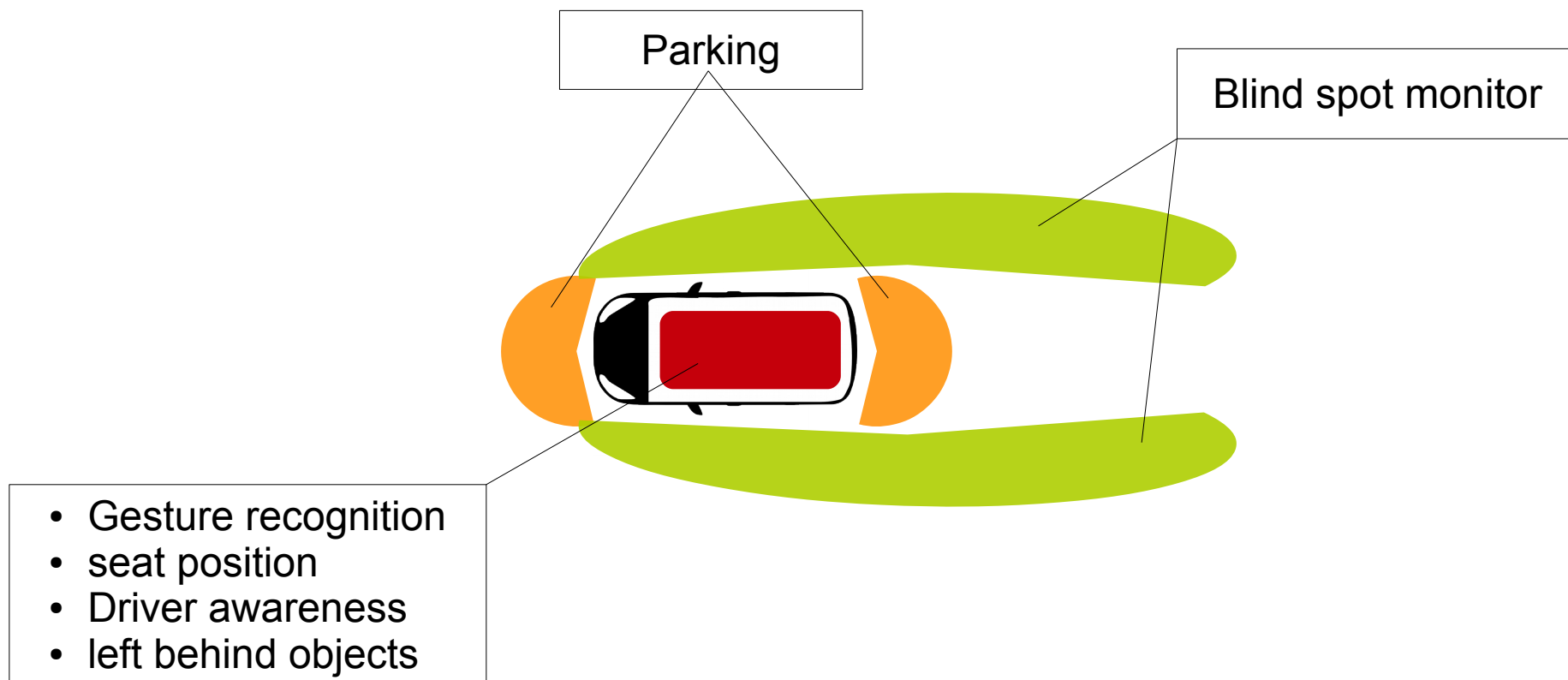


# Future requirements:

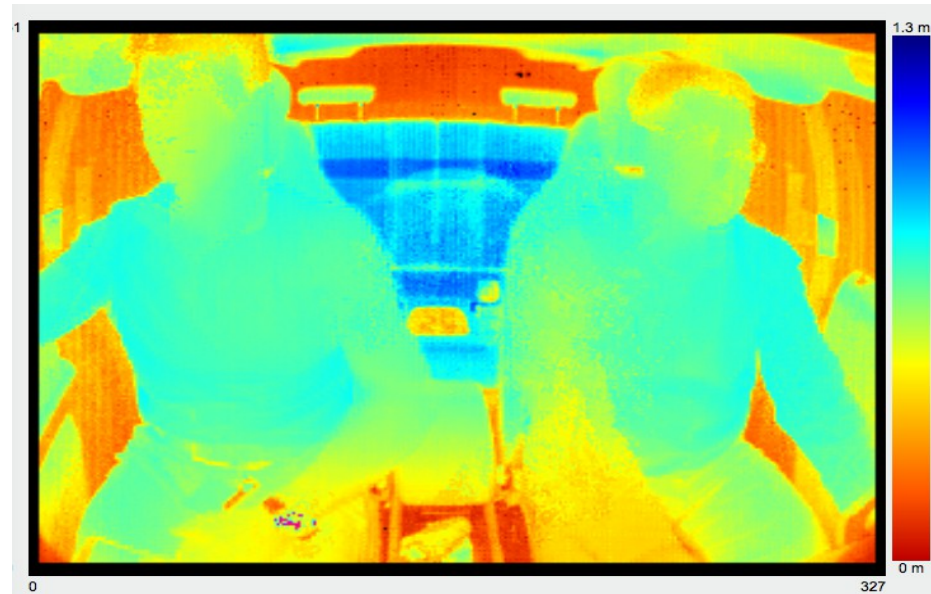
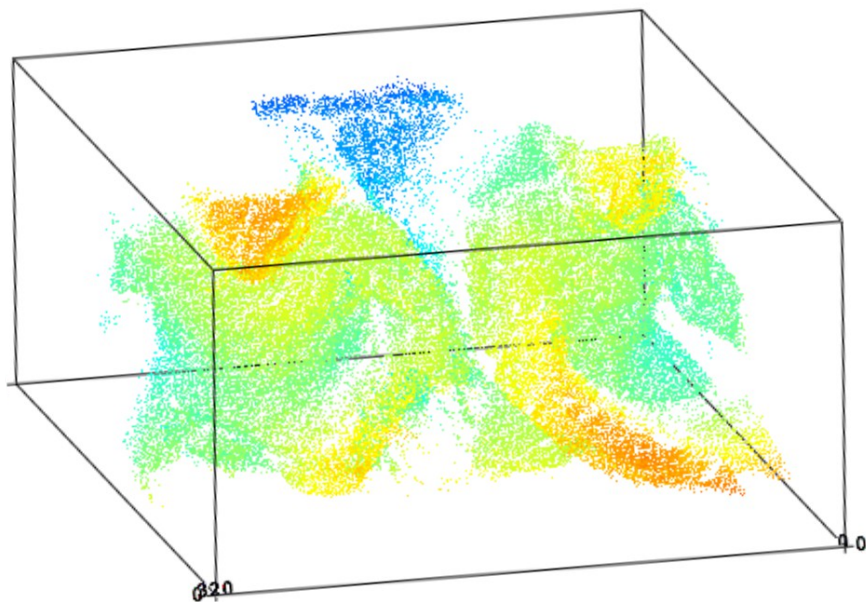
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## Future requirements: close range with cwTOF



# Already existing imaging cwTOF OHC15L™



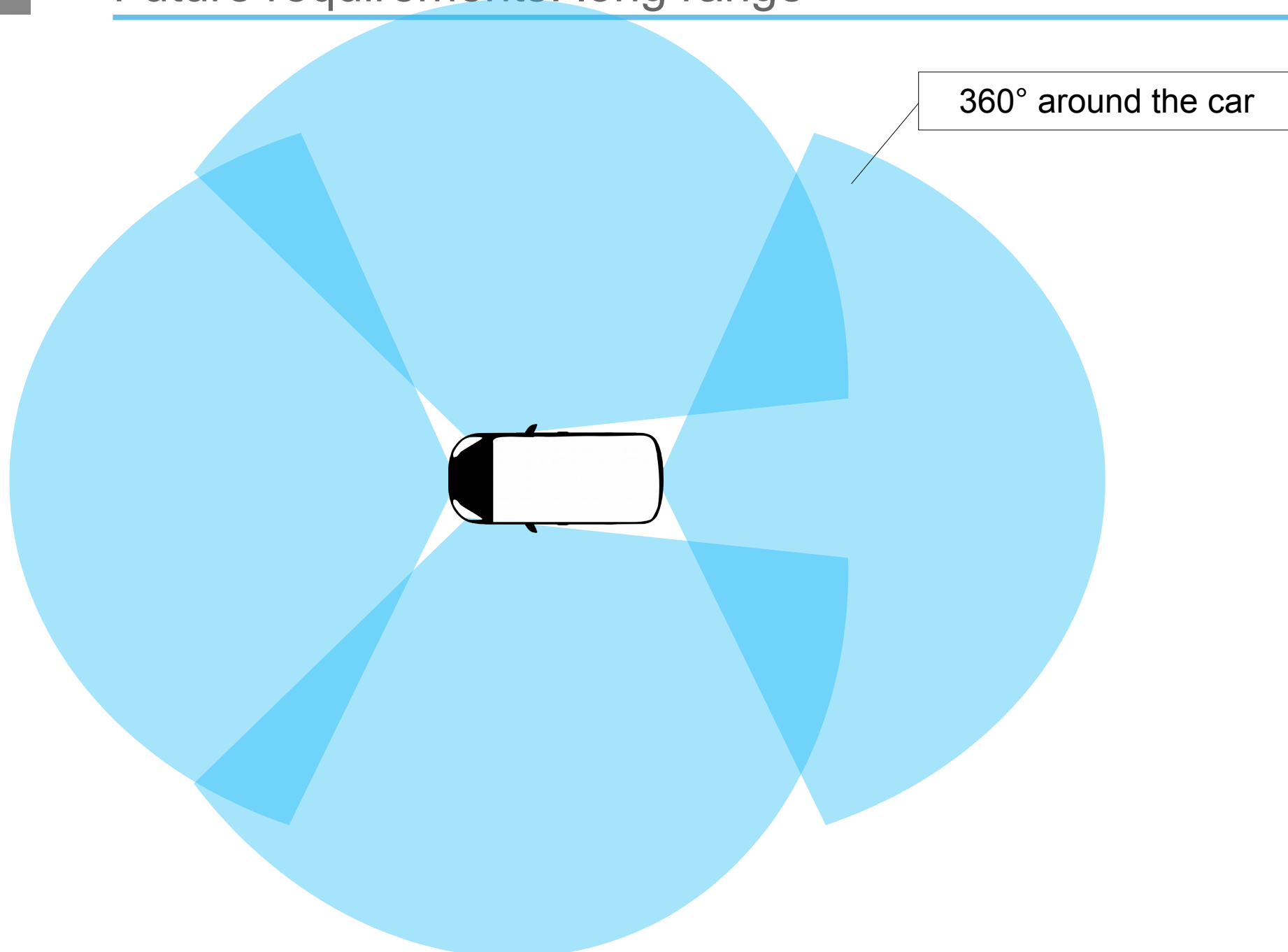
- Lens F# 1.4
- hFOV 94°
- vFOV 70°
- LED power 1W (cw)

- Frame rate 50fps
- Wavelength 850nm
- Range 6m
- Sunlight >100kLux

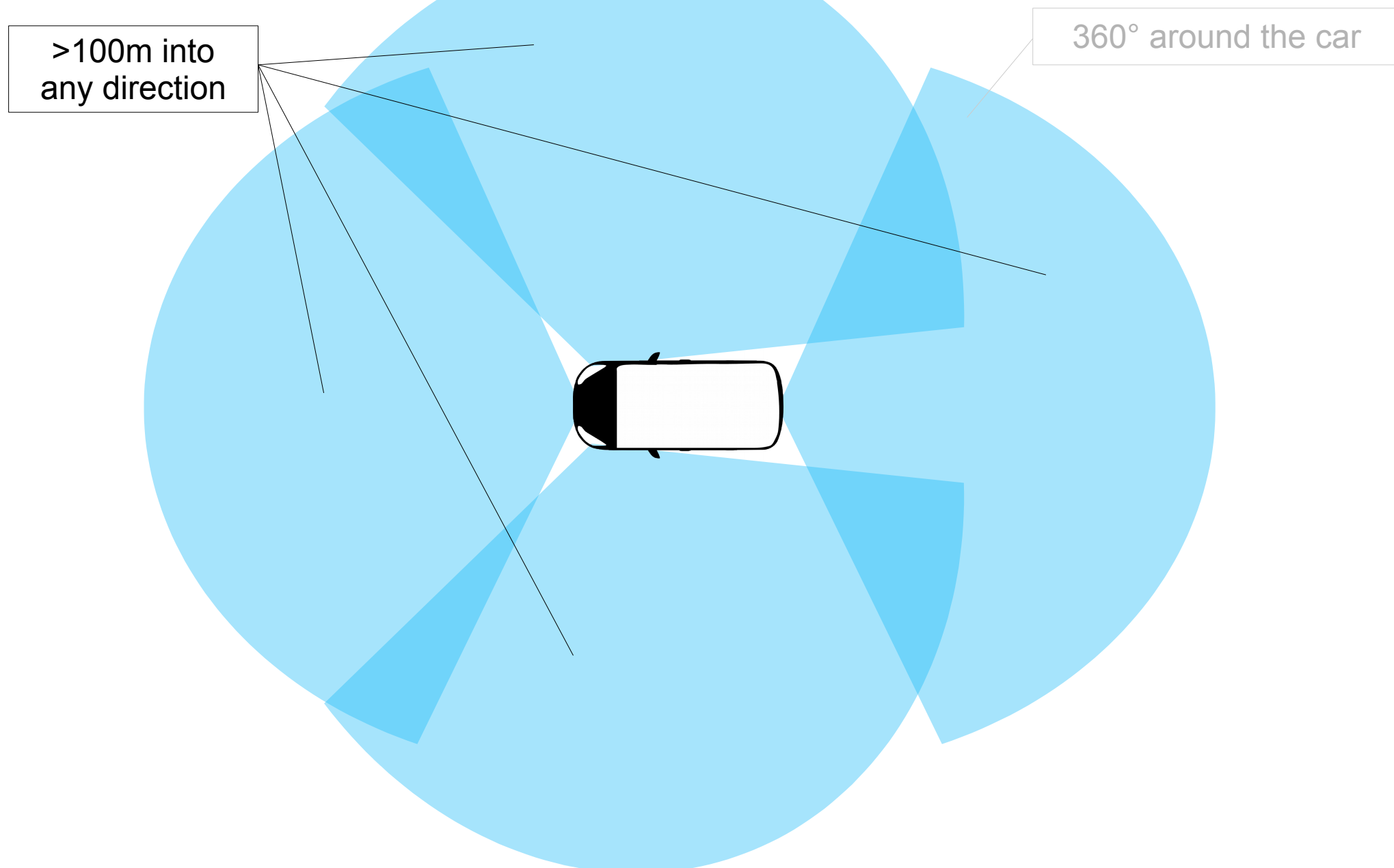
# Future requirements: long range

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## Future requirements: long range

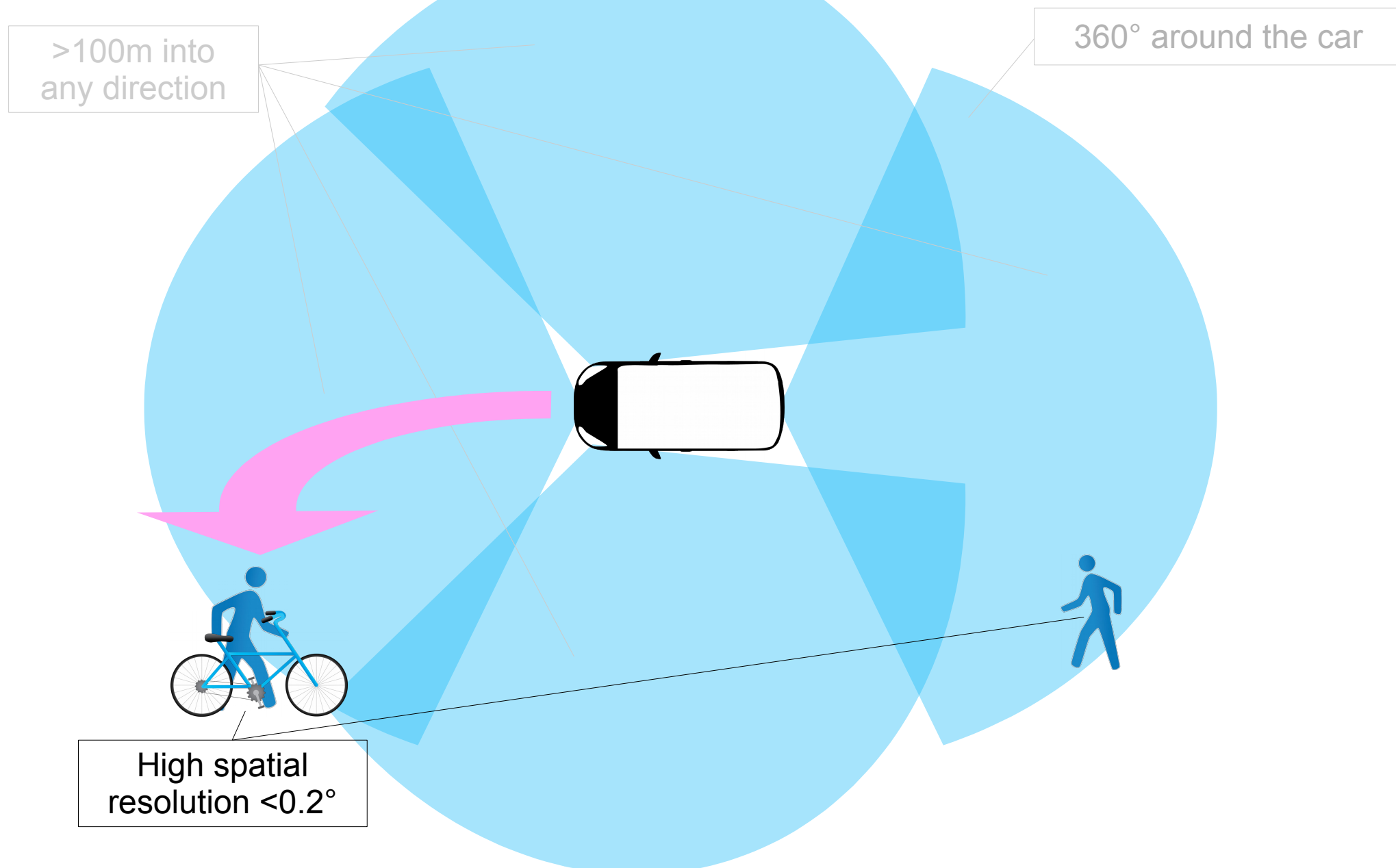


## Future requirements: long range

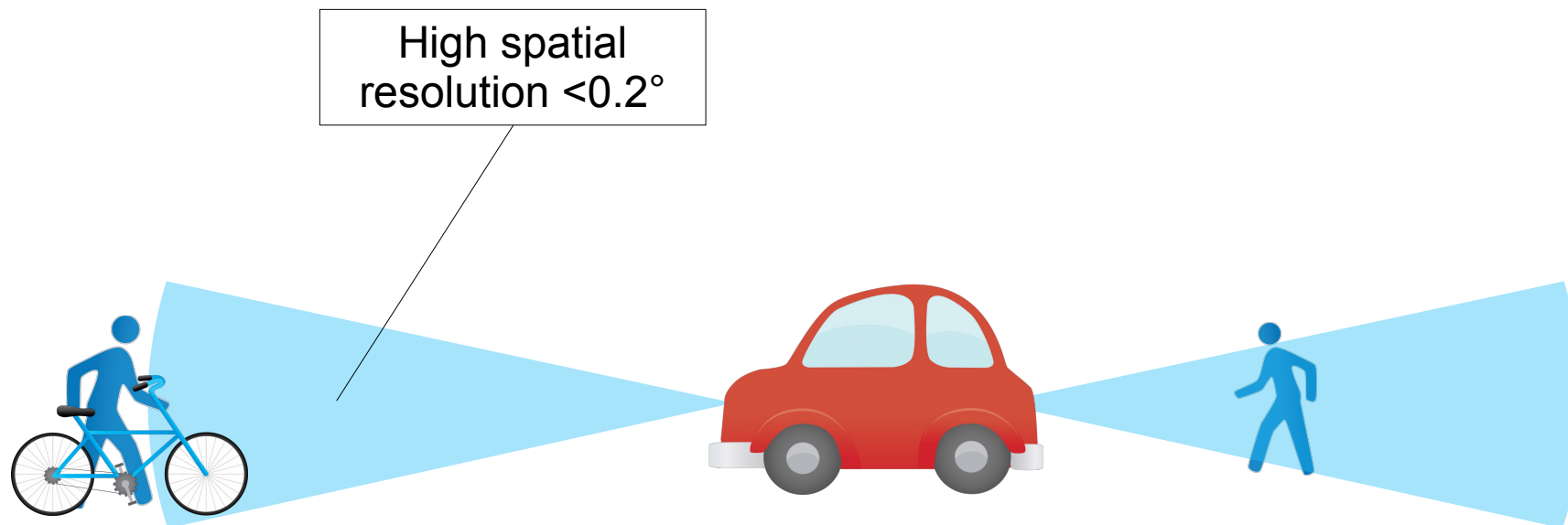




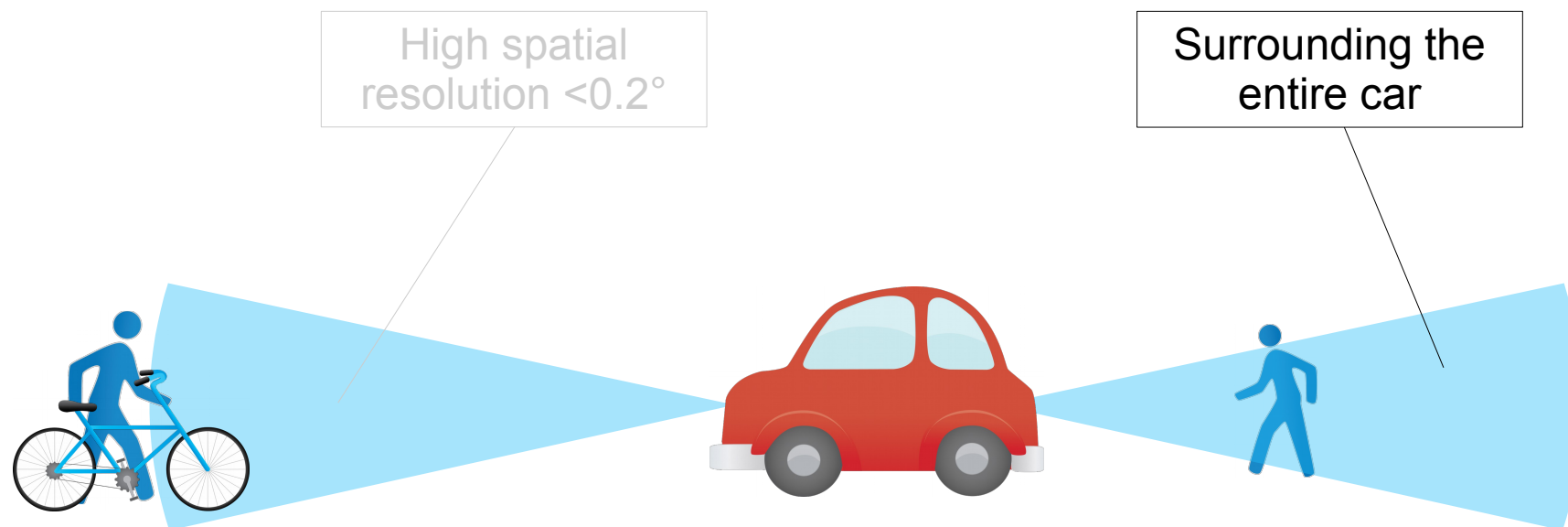
## Future requirements: long range



## Future requirements: Large vertical FOV, high spatial resolution



## Future requirements: Large vertical FOV, high spatial resolution



## Sensor requirements summary

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- Long range >100m
- Range resolution <10cm
- High spatial resolution <0.2°
- FOV horizontal 360°
- FOV vertical >25°
- Weather condition all weather
- Daytime day & night
- Frame rate >25 fps
- Safety eye safe, ASIL
- Multiple sensors no interference
- Cost low

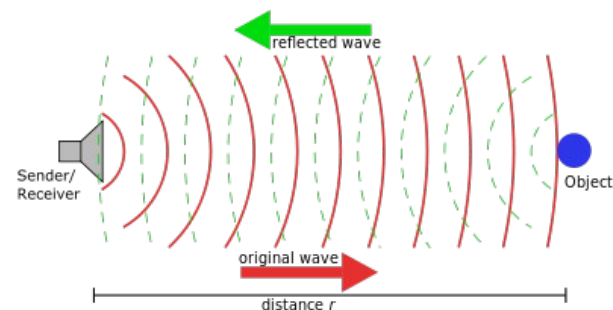
# Sensor technology overview

## Radar



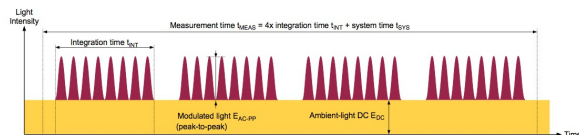
Source: Kaspersky Lab

## Ultrasonic



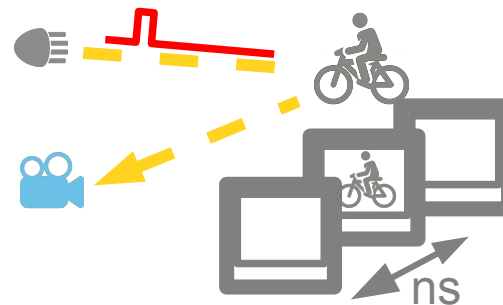
Source: Wikipedia

## cwTOF



Source: ESPROS

## LiDAR

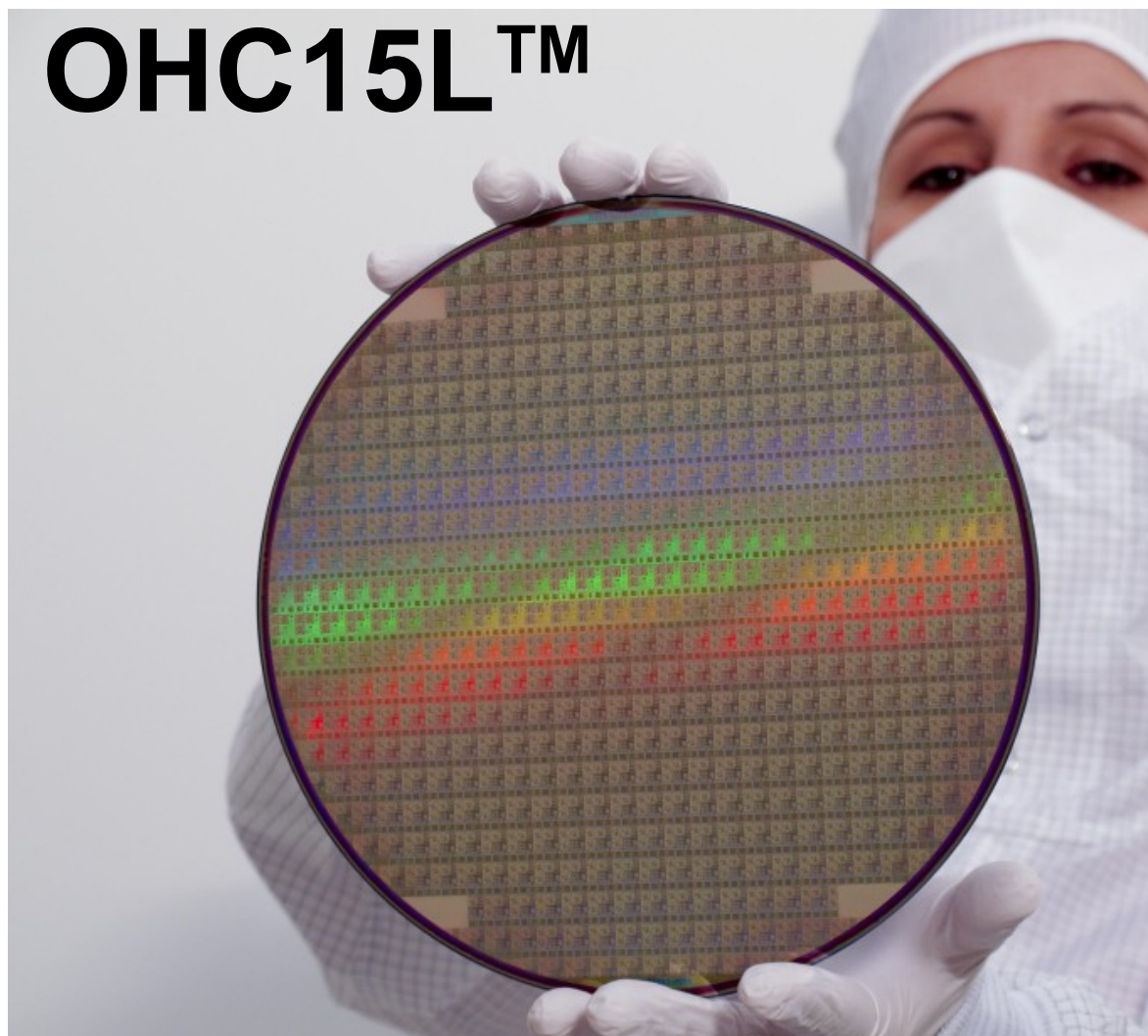


Source: ESPROS

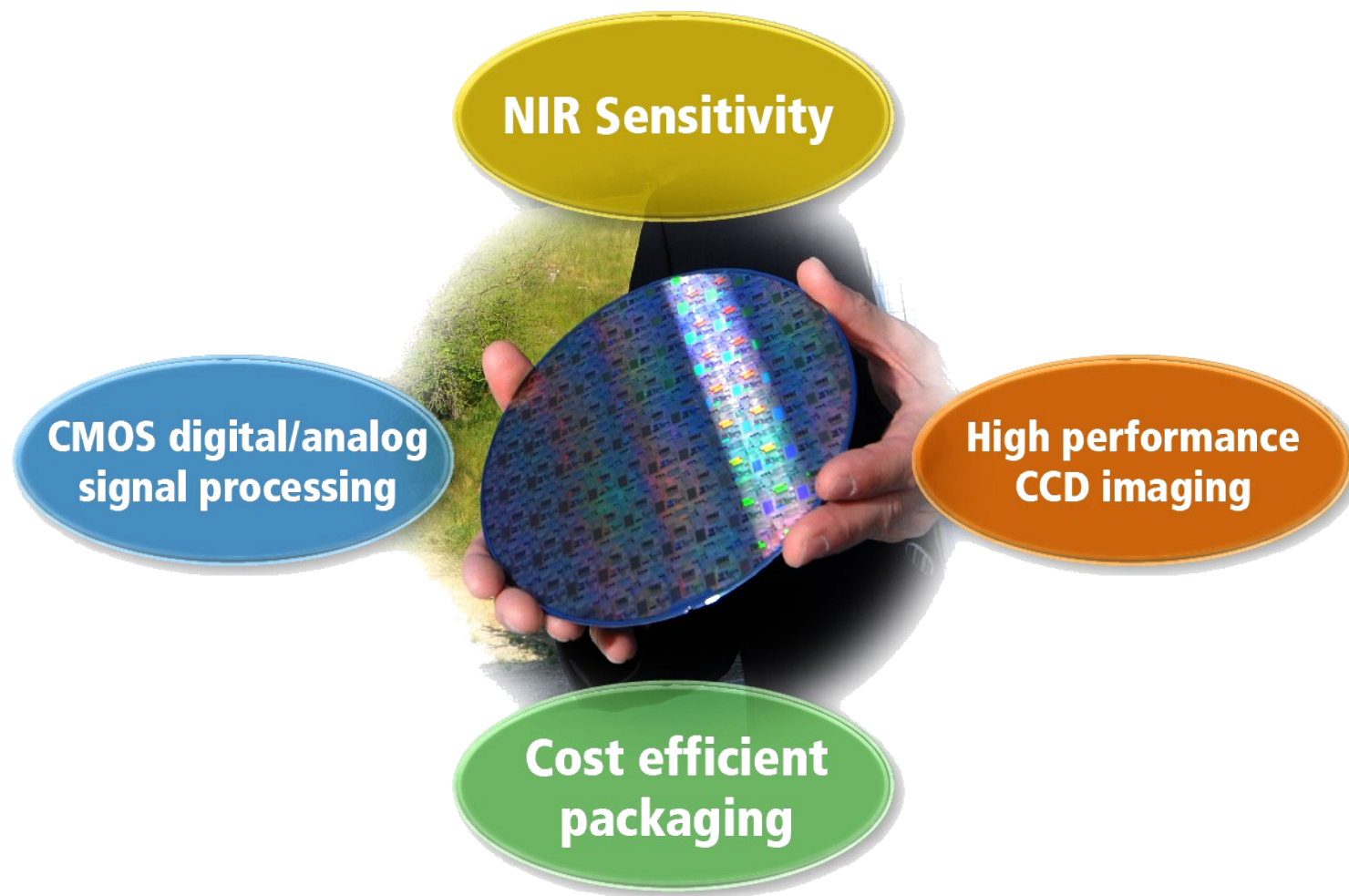
# Technology comparison

Parameter	Requirement	Radar	Ultrasonic	cwTOF	pTOF (Imaging LiDAR)
Long range	$\geq 100\text{m}$				
Short range	0 .. 2m				
Spatial resolution	$\geq 0.2^\circ$				
FOV horizontal	$360^\circ$				
FOV vertical	$\geq 25^\circ$				
Distance resolution	cm				
Weather condition	all weather				
Daytime	day & night				
Response time	>25 fps				
Safety	eye safe, ASIL				
Multiple sensors	no interference				
Cost	low				

# ESPROS imaging LiDAR technology

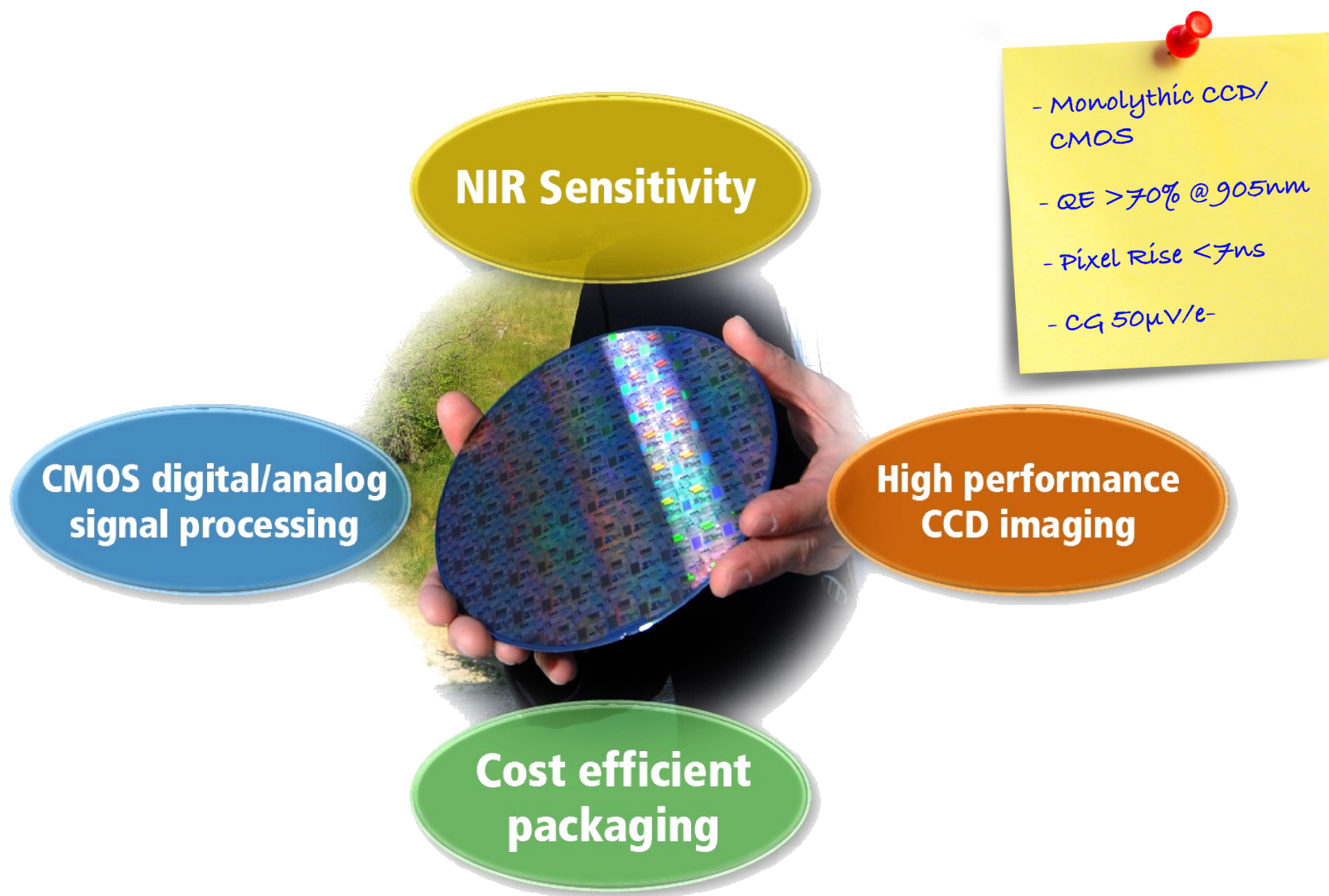


## Key ingredients needed for a good LiDAR imager





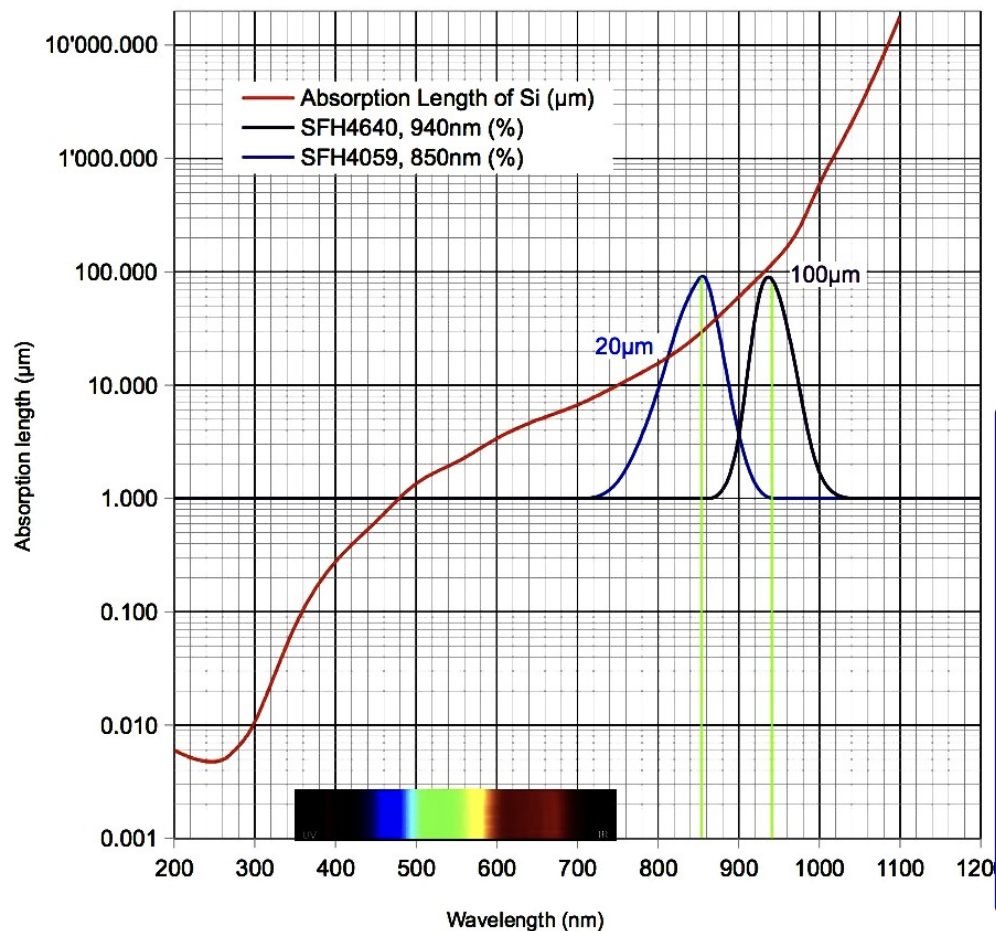
# Key ingredients needed for a good LiDAR imager





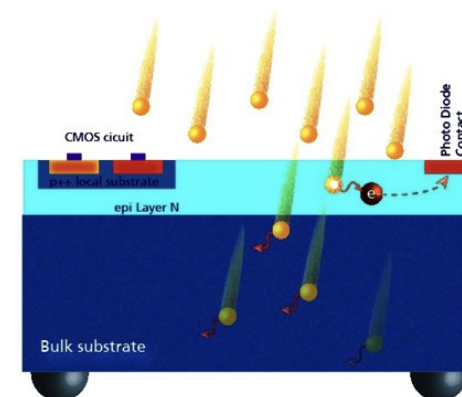
# ESPROS OHC15L™ technical concept

**Absorption length in Silicon**



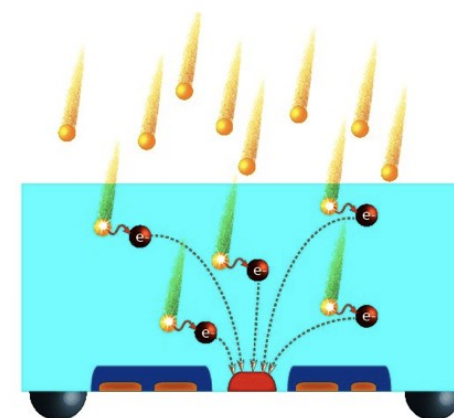
## CONVENTIONAL CMOS

- a) thin active layer
- b) 20% fill factor only



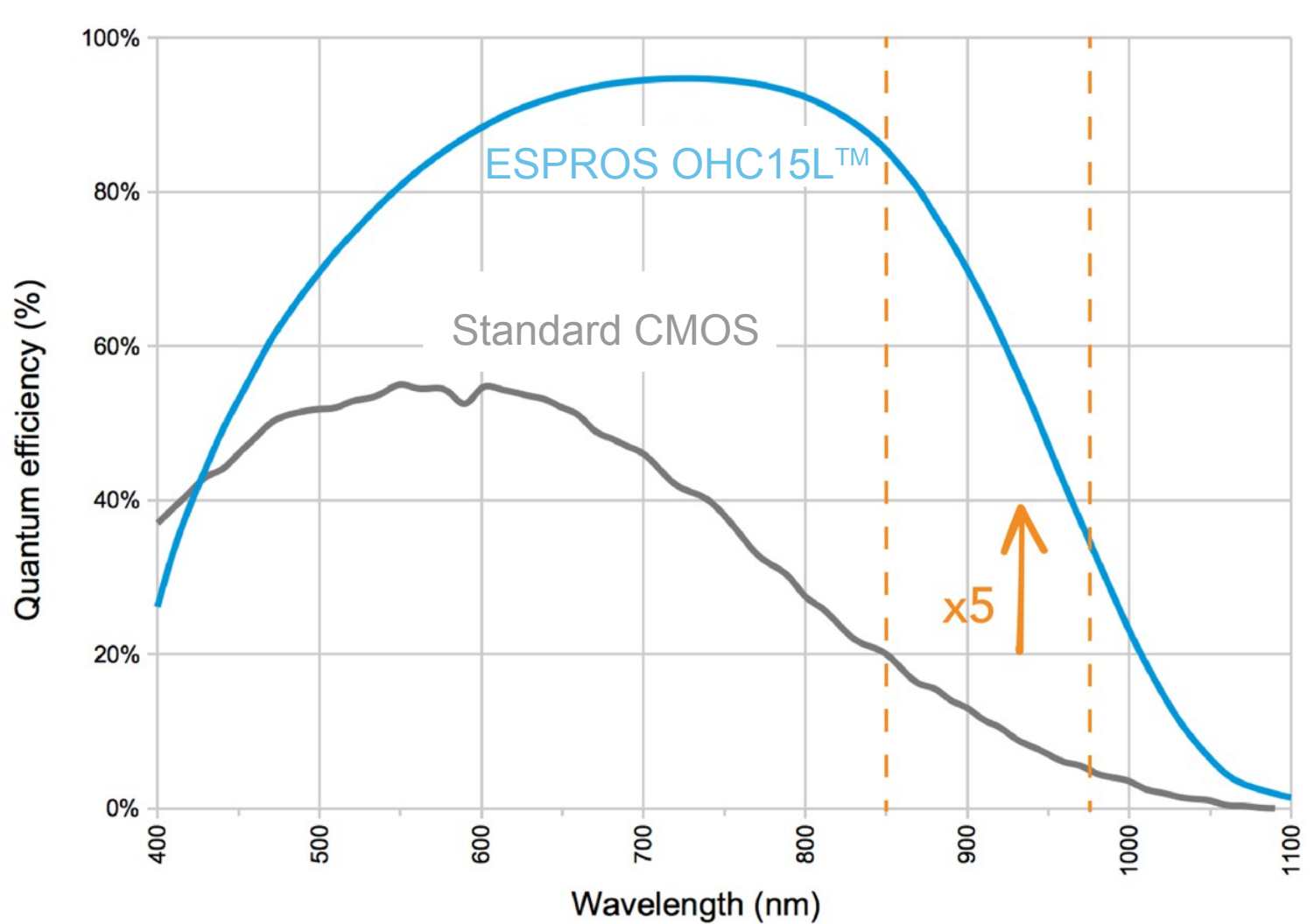
## ESPROS OHC15L™

- a) 50 micron absorber
- b) 100% fill factor

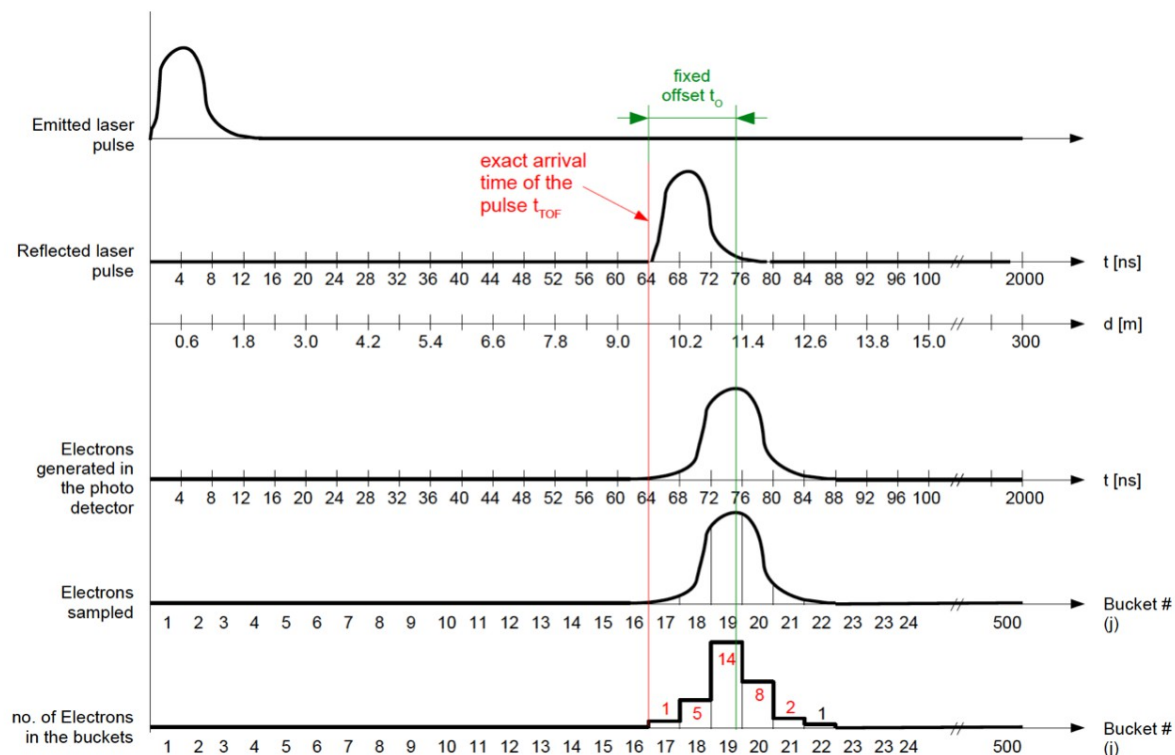




# Quantum efficiency improvement



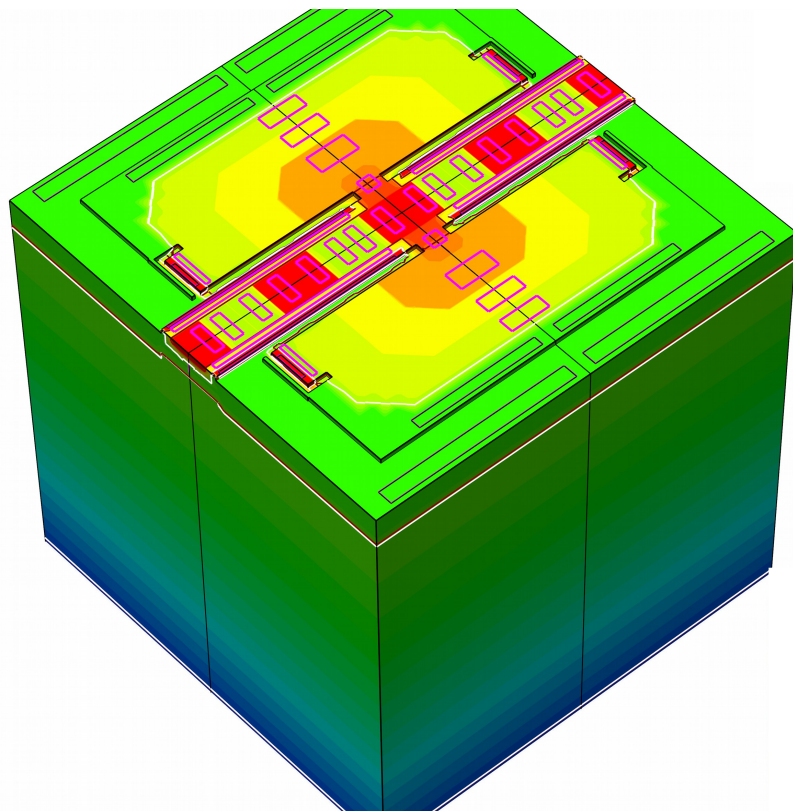
# ESPROS pTOF Principle: Gated imaging with CCD



## Working principle:

- Sampling of arriving light pulses into fast CCD
- A/D conversion of the sampled signal
- Calculation of the exact pulse arrival time point
- Multiple echoes from one laser pulse are detectable

# ESPROS pTOF pixel (example)



## Pixel & imager parameters:

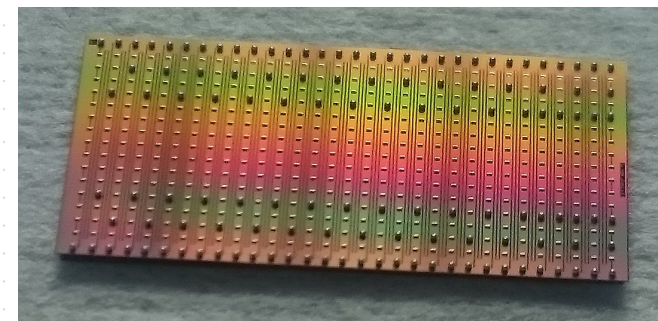
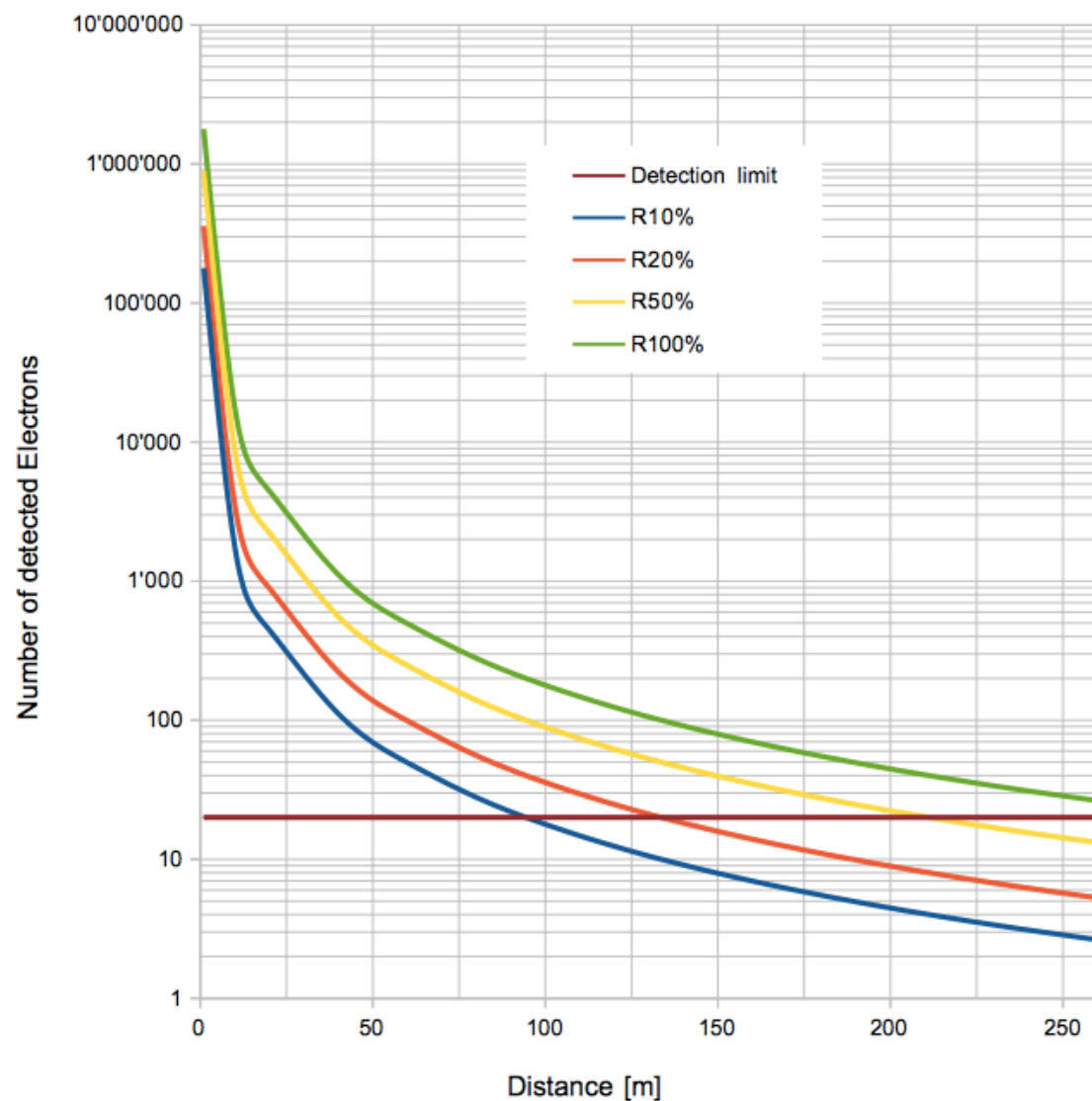
- QE >70% @ 905nm
- Speed 6.5ns (FWHM)
- Sensitivity 20e-
- CCD sampling 250MHz
- CCD 450 stages (270m)
- Pixel pitch 45μm
- Field 262 x 150 pixel
- No. of pixels 38,864
- Frame rate >100fps (full 3D TOF)



# Comparison of receiver device technology

Parameter	APD	SPAD	ESPROS OHC15L™
Rise time	2ns	300ps	6ns
Bias voltage	200V	30V	10V
Max. no. of electrons	unlimited	up to 100	10 <sup>9</sup>
Photo detection efficiency	80%	8%	70%
Min cell distance (pixel pitch)	30μm	25μm	7.5μm
Sensitivity (practical)	15 photons	6 photons	20 photons
Night vision	impossible	poor	good
Typ. Resolution	16 (64)	1,000	40,000
Cost per channel	very high	medium	very low

# ESPROS pTOF operating range performance



LiDAR Imager

## System parameters:

- Lens F# 0.8
- hFOV 50°
- vFOV 25°
- Laser power 3W peak
- Laser pulse 5ns
- Laser Energy 15nJ
- Wavelength 905nm

# At the end: A few words to ESPROS

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# At the end: A few words about ESPROS



## Key data

- Established in 2006
- Privately held corporation
- 70 million CHF initial investment
- Photonics chip design and manufacturing
- 60'000m<sup>2</sup> space built into solid rock for further expansion
- Technology protected with 15 patents or patent applications

## Locations

- HQ Sargans, Switzerland
- Regional offices: USA and China
- 600m<sup>2</sup> class 1-10 cleanroom for backside processing
- 360m<sup>2</sup> class 1000 cleanroom for testing, backend and assembly

## Supply Chain

- Frontside processing of OHC15L™ by TSMC
- Established 2<sup>nd</sup> sources
- Product qualification according JEDEC and AEC-Q100 standards

## Products

- 1, 8x8, 160x60, 320x240 pixel cwTOF image
- Customer specific gated imagers
- Customer specific pTOF imagers

# Thank you!

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