The TOF>frame 611 is a miniaturized and cost optimized 3D TOF camera. It is based on the ESPROS proprietary time-of-flight technology using the epc611 TOF chip and a small LED to illuminate the scenery. The camera controls the illumination and the imager chip to obtain distance and confidence images. Due to the high performance of the imager chip with its unique ambient light suppression, the camera can be used in outdoor applications at full sunlight. This allows a wide variety of new applications, e.g. for mobile robotics. This very small module is easy to use because it delivers fully calibrated and compensated 3D images. All the complex engineering and time consuming design tasks regarding optics, illumination and signal processing are already solved.

### FEATURES

- 8x8 Pixel
- 0.1 – 2m range
- FOV 12° hor/ver
- >50fps
- Light weight 3.7g only
- Low cost
- Low power consumption
- Sunlight tolerant
- Easy to use
- Customized versions possible

### FUNCTIONAL DESCRIPTION

The TOF>frame 611 is a miniaturized and cost optimized 3D TOF camera. It is based on the ESPROS proprietary time-of-flight technology using the epc611 TOF chip and a small LED to illuminate the scenery. The camera controls the illumination and the imager chip to obtain distance and confidence images. Due to the high performance of the imager chip with its unique ambient light suppression, the camera can be used in outdoor applications at full sunlight. This allows a wide variety of new applications, e.g. for mobile robotics. This very small module is easy to use because it delivers fully calibrated and compensated 3D images. All the complex engineering and time consuming design tasks regarding optics, illumination and signal processing are already solved.

### APPLICATIONS

- Gesture Recognition
- In-cabin Monitoring
- Humanoid and Household Robots
- Doors and Gates
- People Counting
- Industrial Automated Guided Vehicles
**SPECIFICATIONS**

- **Range**: 0.1 – 2m
- **Power Consumption**: 5V, 80mA
- **Ambient-light**: 100kLux
- **Resolution**: 8x8 Pixel
- **Interface**: UART 1MBit/s
- **Temperature Range**: -20 - +85°C
- **Accuracy**: ±4cm
- **Data Output**: Resolution 0.1mm, 4 Bytes per Pixel, ROS driver upon request
- **Field of View**: 12° hor/ver

**MECHANICAL DIMENSIONS**

![Mechanical Dimensions Diagram]

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**CONTACT INFORMATION**

- **Headquarters Switzerland**
  - Phone: +41 58 411 03 00
  - Email: sales@espros.com

- **US / Canada Sales Office**
  - Phone: +1 336 837 882
  - Email: sales_us@espros.com

- **China Sales Office**
  - Phone: +86 150 2112 2587
  - Email: sales@espros.cn

www.espros.com